

The field of the invention is medical imaging systems, and particularly, systems for developing software applications for such imaging systems.

Despite the many differences, medical imaging systems have a number of basic functions in common. All medical imaging systems include an operator interface which enables a particular image acquisition to be prescribed, a data acquisition apparatus which uses one of the imaging modalities to acquire data from the subject, an image reconstruction processor for reconstructing an image using acquired data, and storage apparatus for storing images and associated patient information. Typically, hardware is designed to carry out these functions and system software is designed and written for each hardware configuration.

25 A medical imaging system contains application programs which direct the imaging system to perform particular types of scans, image reconstructions and post processing applications. For example, an MRI system may include application software which directs the imaging system

5 MRI system. As the number of applications grows, the amount and complexity of the application software code becomes increasingly difficult to maintain. As a result, the addition of new applications to the imaging system becomes increasingly difficult.

The present invention is an application development system for a medical imaging system, and particularly, a system for producing an object oriented application program from a library of stored components, each component containing methods in the form of executable code and data related to the operation of the medical imaging system. The application development system includes a memory for storing a library of components; a display containing a framework area providing an indication of the components stored in the library, containing a workspace area for indicating components selected from the library to form an application program, and containing a properties area for indicating instance variables of a selected component; an input device; and a processor programmed to enable a user to select with the input device components indicated in the framework area and place them in the workspace area, programmed to edit with the input device instance variables indicated in the properties area for a selected component, and programmed to store the components in the workspace area as an application program.

Application programs may be created without writing and compiling program code. All program code is contained in the components stored in the library and the selection of components and placement in the workspace area of the display links the program code and any modified



Fig. 8 is a pictorial display showing a graphic plot of the rf pulse component of Fig. 7.

## GENERAL DESCRIPTION OF THE INVENTION

Referring particularly to Fig. 5, a medical imaging system includes  
5 imaging apparatus 110 comprised of mechanical and electrical hardware  
elements that are operated during a scan to acquire image data. The  
imaging system also includes data processing apparatus 112 that is  
operated to reconstruct images using the acquired image data. To operate  
the system and to enter a scan prescription an operator input device 114,  
10 such as a keyboard and control panel, is provided, a display device 116 is  
provided to present the images for visualization and a storage device 117,  
such as a hard disc drive, is provided to archive acquired images. The  
particular imaging modality used, and the complexity and power of these  
hardware elements varies substantially from one system to the next.

15 The system includes a workstation 118 which is programmed in a  
machine independent language, such as Java<sup>TM</sup>, to provide a user interface  
120 that enables an operator to enter scan parameters using the operator  
input device 114. The workstation 118 is programmed to produce a scan  
description 122, which in its simplest configuration contains image  
20 acquisition description components and data processing description  
components that contain information required by the imaging apparatus  
110 and data processing apparatus 112 to perform the prescribed scan.

Prior to run time, a snap shot of the scan description 122 is  
downloaded to a plurality of servers which control the imaging system  
25 hardware apparatus. In the simplest configuration these include an image  
acquisition server 124 and a data processing server 126 which operate the  
respective imaging apparatus 110 and data processing apparatus 112.  
When provided with the scan description components, the servers'

programs direct the image system hardware apparatus to perform the prescribed scan. A data store server 113 directs the storage device 117 to save the images along with associated patient information.

The particular scan or operation that is performed by the medical imaging system is directed by an application program stored in the workstation 118.

The application program is produced using an application development system that runs on the workstation 118 or a separate workstation (not shown). The application development system enables the user to create a new application program by selecting objects, or components, written in an object-oriented programming language, from a component library, and assemble them using a visual component assembler. The instance variables of selected components are displayed and may be edited for the new application program. The assembled components are instantiated and saved as a new application program which may be reconstituted for use on the medical imaging system. Instantiation is achieved using a serialization process in which the hierarchical relationship of components and their instance variables are stored.

## DESCRIPTION OF THE PREFERRED EMBODIMENT

Referring particularly to Fig. 1, the preferred embodiment of the invention is employed to operate an MRI system. The MRI system includes a workstation 10 having a display 12 and a keyboard 14. The workstation 10 includes a processor 16 which is a programmable machine commercially available from Silicon Graphics, Inc. It is based on a 64-bit microprocessor manufactured by Intel and it runs the Linux operating system. The workstation 10 provides the operator interface which enables scan prescriptions to be entered into the MRI system. As will be described

in more detail below, the workstation 10 will run one or more Java™ virtual machines which will run code which is programmed in the Java™ language that is fully transportable to any other programmable machine which is Java™ compatible.

- 5           The workstation 10 is coupled to four servers: a pulse sequence server 18; a data acquisition server 20; a data processing server 22, and a data store server 23. In the preferred embodiment the data store server 23 is performed by the workstation processor 16 and associated disc drive interface circuitry. The remaining three servers 18, 20 and 22 are
- 10 performed by separate processors mounted in a single enclosure and interconnected using a 64-bit backplane bus structure based on the PCI standard for industrial and telecommunications applications called "CompactPCI". The pulse sequence server 18 employs a 366 MHz microprocessor model PPC750 and a quad communication controller
- 15 model MPC860T manufactured by Motorola, Inc. The data acquisition server 20 and data processing server 22 both employ the same 366 MHz microprocessor and the data processing server 22 further includes one or more array processors based on parallel vector processors commercially available from Mercury Computer Systems, Inc. as the PowerPC™.
- 20 Another 366 MHz microprocessor (not shown) serves as a hardware controller on the PCI bus structure and it controls a quad communication controller model MPC860T manufactured by Motorola, Inc.

- The workstation 10 and each processor for the servers 18, 20 and 22 are connected to a 100 BaseT Ethernet serial communications network.
- 25 This serial network conveys data that is downloaded to the servers 18, 20 and 22 from the workstation 10 and it conveys tag data that is communicated between the servers and between the workstation and the servers. In addition, a high speed data link using the BIT3 protocol is

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receives commands to move the patient to desired positions during the scan.

It should be apparent that the pulse sequence server 18 performs real-time control of MRI system elements during a scan. As a result, it is necessary that its hardware elements be operated with program instructions that are executed in a timely manner. As will be explained in more detail below, the pulse sequence server 18 is controlled during run-time by programs written in a low level programming language such as assembler, C or C++. The description components for a scan prescription are downloaded from the workstation 10 in the form of objects. The pulse sequence server 18 contains programs which receive these objects using a serialization mechanism. The pulse sequence server 18 also includes a program which converts the objects to C++ objects that are employed by the run-time programs. In the preferred embodiment Java™ objects are downloaded and the Java™ serialization mechanism is employed. The pulse sequence server 18 thus includes both hardware independent programs written in Java™ and hardware dependent programs. It is contemplated that Java™ interpreters will eventually become fast enough that nearly all programs run on the pulse sequence server 18 will be written in hardware independent form.

The digitized NMR signal samples produced by the RF system 26 are received by the data acquisition server 20. The data acquisition server 20 operates in response to description components downloaded from the workstation 10 to receive the real-time NMR data and provide buffer storage such that no data is lost by data overrun. In some scans the data acquisition server 20 does little more than pass the acquired NMR data to the data processor server 22. However, in scans which require information derived from acquired NMR data to control the further performance of the scan, the data acquisition server 20 is programmed to produce such



information and convey it to the pulse sequence server 18. For example, during prescans NMR data is acquired and used to calibrate the pulse sequence performed by the pulse sequence server 18. Navigator signals may be acquired during a scan and used to adjust RF or gradient system operating parameters or to control the view order in which k-space is sampled. And, the data acquisition server 20 may be employed to process NMR signals used to detect the arrival of contrast agent in an MRA scan as described in co-pending U.S. Pat. Appln. Serial No. 08/635,078 filed April 19, 1996 and entitled "*Method For Performing Magnetic Resonance Angiography Using a Contrast Agent*". In all these examples the data acquisition server 20 acquires NMR data and processes it in real-time to produce information which is used to control the scan.

As with the pulse sequence server 18, the hardware elements of the data acquisition server 20 are operated at run-time with program instructions in a programming language such as assembler, C or C++. As will be explained in more detail below, the directions for its operation during a scan are downloaded from the workstation 10 in the form of objects. A server proxy receives the objects using the serialization mechanism and the downloaded objects are converted to C++ objects that are employed to operate the data acquisition server 20 during run-time. As indicated above, Java™ objects are downloaded in the preferred embodiment using the Java™ serialization mechanism.

The data processing server 22 receives NMR data from the data acquisition server 20 and processes it in accordance with description components downloaded from the workstation 10. Such processing may include, for example: Fourier transformation of raw k-space NMR data to produce two or three-dimensional images; the application of filters to a reconstructed image; the performance of a backprojection image



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The application container also includes scan descriptions 50. These scan descriptions are downloaded to the servers 18, 20, 22 and 23 (Fig. 1) and used by those servers to perform the prescribed scan. The stored scan descriptions 50 are unique for every different application.

After the application program is developed, the application container object is serialized and stored in the disc storage 44. When the operator of the MRI system selects the application program, the corresponding  
25 serialized application container object is read from the disc memory 44 and reconstituted as shown in Fig. 2 to operate the MRI system. To better understand the requirements of the application development system, the

operations performed by the MRI system under the direction of the application program will now be described.

The application controller 46 includes an application state object 48 which maintains the state of the application as the scan is performed. The possible states during a life cycle of an application are as follows:

- Initialization
- Prescribing
- Prescribed
- Downloading
- Downloaded
- Prescanning
- Prescanned
- Batch Scanning
- Real Time Scanning
- Scan Paused
- Scanned
- Reconstructed
- Visualized.

This life cycle is driven by commands from the application container (like initialize application), by commands from the operator (like start scan) and by commands generated internally by the application (like scan done).

When the operator initially selects the application, the application initializes and changes to the "prescribing state" and the prescription controller 52 is enabled to interact with the scan description components 50 to determine what scan parameters must be specified by the operator (e.g. TR, number of slices, location of FOV, flip angle) and determine if the prescription is complete and valid. The prescription controller 52 then

signals the application state object 48 to switch to the "prescribed" state and download, prescan and scan buttons on the control panel are enabled.

If the operator hits the "download" button, the application state object 48 changes to the "download state" and the application controller 46  
5 employs a snap shot controller 54 to issue snap shot and download commands. As will be described in more detail below, these commands cause the scan descriptions 50 to be downloaded to the servers 18, 20, 22 and 23. The snap shot controller 54 receives "download done" notification back from each of the servers 18, 20, 22 and 23, and when all four servers  
10 have been downloaded, the application state object 48 is changed to the "downloaded" state.

If the operator hits the scan button, the application state object 48 will change to the scan mode and a scan controller 56 is employed to issue a scan command to the pulse sequence server 18. The next state  
15 transition is governed by the scanning mode i.e., real-time or batch. The behavior of the application in the two modes is very different and so there are two different scanning states. If in real-time mode, the application is set to a "real-time scanning" state and if in batch mode, the application state is set to a "batch scanning" state. When in the real-time mode, if the user  
20 chooses to pause the scan, the application will transition to a "scan paused" state. If scanning is resumed, the application goes back to the real-time scanning state. In real-time scanning state, the application can be edited and edited descriptions will be downloaded even while the scanning is in progress. However, the application will not make a state transition; instead,  
25 the same state will be characterized to allow editing and downloading. It is this behavior of the real-time scanning state that differentiates it from the batch scanning state.

The application will make a transition to the "scanned" state when the operator hits the "stop scan" button. Also, if the application is in the

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batch scanning mode of operation, the pulse sequence server 18 notifies the application controller 46 when the scan is completed. The application state object changes to the “scanned” state in either event.

When the data processing server 22 completes reconstruction of the  
5 acquired images, the application controller 46 is notified and the application  
state object 48 is changed to the “reconstructed” state. This indicates to  
the workstation 10 that reconstructed images are available on disk 44 for  
display or further processing.

The scan descriptions 50 contain a set of components that serve to collect scan parameters using the prescription controller 52, and to organize those prescription scan parameters into a set of smaller components that can be downloaded to the servers 18, 20, 22 and 23. On the servers 18, 20, 22 and 23, those downloaded components direct the operation of the hardware in order to carry out the prescribed scan.

15           There are different description types within each application to provide logical groupings of components to deal with different aspects of executing an MR scan. These description types are:

20      Pulse Description;  
Sequence Description;  
Acquisition Description;  
Data Processing Description;  
Data Store Description.

The pulse description includes components that define and control the waveforms to be played out on the gradient system and the RF system hardware, along with hardware control components. These components control the dynamic aspects of the waveforms and hardware in response to events produced at run-time by components of the sequence description. This description also includes components that control the filtering of NMR

signals received by the RF system 26. These components collectively define a unique set of gradient/RF/control pulses which are used to excite, encode, and readout the NMR signals. Examples are pulse descriptions for 2D spin echo, 2D gradient-echo, 2D fast spin-echo, and 3D gradient-echo sequences.

The sequence description includes a set of components that control the order of pulse sequences played out, and define a series of prescribed events along the scan timeline. These prescribed events defined by the sequence description trigger the dynamic behavior of the pulse components in the pulse description. These components prescribe a unique acquisition ordering used to define the slice and k-space sampling order. Examples are 2D sequential, 2D interleaved, 3D sequential, 3D elliptical centric, and multi-slice CINE.

The acquisition description includes a set of components that prescribe the real-time processing of NMR signals acquired by the RF system 26. These components direct the performance of operations on acquired NMR signals to produce information that is fed back to components in the sequence description to affect subsequent scanner operation. These components may, for example, process NMR signals during a calibration prescan to feedback changes in the power or frequency of RF pulses produced during the subsequent scan; or process NMR signals to detect when a bolus of contrast agent arrives in a region of interest and trigger the start of a centric view order acquisition; or process "navigator" NMR signals to produce phase correction information which may be used to alter the view order of the scan or alter the demodulation reference frequency of the RF system 26. There are scans commonly used in clinical applications which do not require this capability, however, and in those applications, the components in the acquisition description simply

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buffer or filter the acquired NMR signals and make them available to the data processing server 22.

The data processing description contains components that direct the data processing server 22 to transform acquired NMR signals into a meaningful form. Image reconstruction is the most common function and the resulting form is a 2D or 3D image of the subject being scanned. Spectroscopy processing can also be defined by these components, in which case the form that results is an image of the spectra of the acquired NMR signals.

- 10        The data store description contains components that define the images which are stored in the database during a scan. In addition to the reconstructed images, this may include patient information and scan parameter information which is to appear annotated on the image along with the patient anatomic or spectrographic information.
- 15        As indicated above, the application development system is implemented on a workstation having a memory, a display, an input device such as a keyboard and mouse and a processor programmed to perform the functions now to be described. Referring particularly to Figs. 3 and 4, the programs and data which form the software architecture of the
- 20        application development system includes a visual component assembler 60 which produces a window display 62 to the user that contains three areas: a framework area 64; a workspace area 66; and a properties area 68. The application program is developed by selecting components from the component library 72 which are displayed in the framework area 64 and
- 25        dragging them into the workspace area 66. Such selected components are stored in workspace storage 67. The properties of a selected component in the workspace area 66 are displayed in the properties area 66, and these properties can be changed using an property editor 70.

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The components displayed in the framework area 64 are Java™ classes, or objects stored in a component library 72. These components are typically developed using a commercially available integrated development environment 74 such as that sold under the trademark "Forte for Java" by Sun Microsystems or "JBuilder" sold by Inprise. The components are written in Java™ source code and compiled into binary instructions called byte code. These byte code components are saved to the appropriate packages in the component library 72. It can be appreciated that many Java components are commercially available and these can be used along with custom written Java components to create more complex components specifically applicable to performing the MRI functions described above. The objective is to create and store enough components in the component library 72 such that a user can build any desired application by selecting existing components. In such case, the user does not need to write any software code to implement new applications, but is simply requested to select and aggregate the desired functionality.

Referring particularly to Figs. 3, 4 and 6, as components are dragged into the workspace 66 from the framework area 64, the visual component assembler 60 establishes the hierarchical relationship between the components. These relationships are illustrated in one preferred manner in Fig. 4 by the indentation of containee component icons beneath their related container component icon. An alternative embodiment of the display of this hierarchical relationship of components in the workspace 66 is shown in Fig. 6. In this embodiment, arrows point from each superclass component icon to its related subclass component icons. It can be appreciated that the display of a complete application requires more display area than is available and that scroll bars may be used to display different portions of the application in the workspace 66.

To build an application, the user first loads the framework area 64 with the library of components. The components are displayed and an application container component 76 is selected. When this component 76 is dragged to the workspace 66, components for all of its children are also identified. This initiates the building of an application, but the user must know what further components are required to complete the build. To assist in this effort any component in the workspace 66 can be selected with a right click of the mouse and a description of the function performed by that component is displayed in the format known as Javadoc™.

- Each component in the workspace 66 has properties, which include numeric variables, Boolean variables and other class type or named variables. The visual component assembler enables the user to display these properties in the properties area 68 by left clicking on a selected component. If the user then left clicks to select one of the displayed properties in the properties area 66, the property editor tool 70 is employed to enable the user to make the change. It is contemplated that most of the new applications created in clinical settings will be limited to changing the properties in components of existing applications. In other words, existing applications are dragged from the framework area 64; the properties in selected components therein are edited; and the result is saved back to the component library 72 as a new application.

- When the application is completed the selected components assembled in the workspace area 66 are then persisted. This is currently accomplished by storing the application using the above described serialization mechanism, however, other persistence mechanisms are known and may be used. The persistence mechanism stores the hierarchical relationship ("graph") between the selected components as well as the instance variable (property) values. The byte code for each component in the application is not stored with the persisted application.

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The medical imaging system which employs the application must itself store the byte code for all the components used in applications. When the persisted application is restored, or "deserialized", on the MRI system, it directs the loading of the byte code indicated by the persisted object graph and instance variable.

Because many of the components in MRI applications relate to the production of pulses and pulse sequences, another feature of the present invention is the display of waveforms or other data produced by a component. Referring particularly to Figs. 3, 7 and 8, all components, may include a property called a "visible." In the case of a pulse waveform component, when the visible property is switched to "true", a waveform plotter 78 is enabled and a pulse sequence plotter window 80 is produced and displayed. This window 80 displays the waveforms 82 and 84 which are produced by this instance of the component. If a property is changed using the editor 70, the displayed waveforms may also change. This is illustrated in Fig. 8 when the property "pulse type" is about to be changed.

When the application is complete, the application container object is serialized and saved to storage. As indicated above, this serialized form of the application program may be restarted in another virtual Java™ machine such as the MRI system described above and reconstituted into an object-oriented application program ready for execution.

One advantage of the serialized configuration of the stored application program is that it can efficiently be downloaded to clinical MRI systems from remote sites. This may be done through direct serial connection using a private Intranet or a public telephone system, or it may be done through the Internet public system. In any case, the transfer of the application program is a serialized object stream which carries the class name of each object, or component, as well as that component's instance data which is described by attribute name, type, and value. Also

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transferred is the relationships between components which allows a graph of the components in the application program to be collected in the serial stream received at the MRI system and then recreated, or reconstituted, on the MRI system. The serialization mechanism follows all relationships

- 5 between objects. Each object, or component in the graph is only serialized once. Should a component be referenced more than one time, the serialization process recognizes the repeat and inserts a reference to the previous occurrence in the graph. This prevents duplication of objects and reduces the magnitude of the download task.

- 10 The serialization process also eliminates the need for downloading byte code. This presumes that any MRI system that receives a downloaded application program has a library which stores the byte code for all components contained in the application program. Updates to clinical systems may, therefore, include both the downloading of new
- 15 applications as well as the downloading of any necessary new components for the MRI system library.

- Of course, the serialization process also enables applications to be uploaded from clinical MRI systems. This enables applications and/or components developed at clinical research systems to be uploaded to the
- 20 MRI system manufacturer for review and analysis.

- The application development system can also be operated in a simulation mode to try out the application program before an actual scan is performed on the MRI system hardware. This simulation capability is facilitated by the fact that the application program will run on any Java™
- 25 virtual machine with a suitable component library. It is also facilitated by the fact that the user interface is a component of the application, such that the simulation uses the same interface and displays the same information as when running on an MRI system. Simulation environment is a mode of operation of the application development system which allows a developer

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to test and debug his/her application in a near-scanner like environment. The Java application loaded in the component assembler collection can be first saved and then simulation may be started. During simulation, the servers are in "simulation mode" and thus certain hardware interfaces are emulated or non-functional. Typically raw data is injected into the server imaging chain to be processed as it would if received by the transceiver.

During application simulation, the developer will have the opportunity to do certain levels of message tracing and component debug. The developer is provided with several levels of component message tracing, which can be set dynamically during application simulation. The developer may also invoke several levels of debug. During component and application development, the developer can set a "debug=TRUE" property in each component in order to access custom debug behavior for that component. Or, there may be several levels of debug for a property, with "0" being none or "debug off". For example, the sequencing component of the sequence description may provide for single stepping of the slice and phase encoding looping. Any custom user interfaces required for a given component are provided by that component in debug mode.

There may also be one or more simulation user interfaces which can be accessed during simulation to provide access to more global operations, such as observing the internal behavior of a specific server, inter-server tag communications or perhaps observing detailed behavior of a specific server, including tags and agent behavior.

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